Incremental 25-mm-dia. Rotary Encoder

E6A2-C

CSM_E6A2-C_DS_E_5_1

Compact Encoder with External Diameter of 25 mm

- Incremental model
- External diameter of 25 mm.
- Resolution of up to 500 ppr.



CE

Be sure to read *Safety Precautions* on page 3.

Ordering Information

Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Output phases	Resolution (pulses/rotation)	Model
5 to 12 VDC	Voltage output	Phases A, B, and Z	100, 200, 360	E6A2-CWZ3E (resolution) 0.5M
	Vollage output		500	Example: E6A2-CWZ3E 100P/R 0.5M
	Open-collector output (NPN output)		100, 200, 360	E6A2-CWZ3C (resolution) 0.5M
			500	Example: E6A2-CWZ3C 100P/R 0.5M
12 to 24 VDC			100, 200, 360	E6A2-CWZ5C (resolution) 0.5M
			500	Example: E6A2-CWZ5C 100P/R 0.5M
5 to 12 VDC	Voltago output	Phases A and B	100, 200, 360	E6A2-CW3E (resolution) 0.5M
	vollage oulput		500	Example: E6A2-CW3E 100P/R 0.5M
	Open-collector output (NPN output)		100, 200, 360	E6A2-CW3C (resolution) 0.5M
			500	Example: E6A2-CW3C 100P/R 0.5M
12 to 24 VDC			100, 200, 360	E6A2-CW5C (resolution) 0.5M
			500	Example: E6A2-CW5C 100P/R 0.5M
5 to 12 VDC	Voltago output	Phase A	10, 20, 60, 100, 200, 300, 360	E6A2-CS3E (resolution) 0.5M
	Vollage output		500	Example: E6A2-CS3E 10P/R 0.5M
	Open-collector output (NPN output)		10, 20, 60, 100, 200, 300, 360	E6A2-CS3C (resolution) 0.5M
			500	Example: E6A2-CS3C 10P/R 0.5M
12 to 24 VDC			10, 20, 60, 100, 200, 300, 360	E6A2-CS5C (resolution) 0.5M
			500	Example: E6A2-CS5C 10P/R 0.5M

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks		
Coupling	E69-C04B	Provided with the product.		
Servo Mounting Bracket	E69-1	Provided with the E6A2-CWZ		

Refer to Accessories for details.

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Ratings and Specifications

Item	Model	E6A2- CWZ3E	E6A2- CWZ3C	E6A2- CWZ5C	E6A2-CW3E	E6A2-CW3C	E6A2-CW5C	E6A2-CS3E	E6A2-CS3C	E6A2-CS5C
Power su voltage	pply	5 VDC –5% to 12 V +10% ripple (p-p): 5% max.		12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC –5% to 12 V +10%, ripple (p-p): 5% max.		12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC -5% to 12 V +10%, ripple (p-p): 5% max. (p-p): 5% max. (p-p): 5%		12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.
Current consumpt	tion*1	50 mA max.	50 mA max. 30 mA max.		30 mA max.	20 mA max.		30 mA max. 20 mA max.		
Resolutio rotation)	n (pulses/	100, 200, 360,	500		1	1		10, 20, 60, 100, 200, 300, 360, 500		
Output ph	nases	Phases A, B, a	and Z		Phases A and B			Phase A		
Output co	onfiguration	Voltage out- put NPN open-collector output		lector output	Voltage out- put	NPN open-collector output		Voltage out- put	NPN open-collector output	
Output ca	apacity	Output resis- tance: 2 kΩ Output cur- rent: 20 mA max. Residual volt- age: 0.4 V max. (Output cur- rent: 20 mA max. Residual volt- Residual volt- Residual volt (at sink current: 20 mA max.		e: 30 VDC 10 mA max. ge: 0.4 V max. t of 30 mA)	Output resistance: $2 k\Omega$ Output cur- rent: 20 mA max. Residual volt- age: 0.4 V max. (Output cur- rent: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		Output resistance: $2 k\Omega$ Output cur- rent: 20 mA max. Residual volt- age: 0.4 V max. (Output cur- rent: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)	
Maximum frequency	response /*2	30 kHz								
Phase diff	ference outputs	Phase difference between phases A and B: 90°±45°								
Output du	uty factor							50±25%		
Rise and fall times of output		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)	
Starting to	orque	1 mN·m max.	1 mN·m max.							
Moment o	of inertia	1 × 10 ⁻⁷ kg⋅m ²	max.							
Shaft	Radial	10 N								
loading	Thrust	50 N								
Maximum permissib	l ble speed	5,000 r/min								
Ambient to range	emperature	Operating: -10 to 55°C (with no icing), Storage: -25 to 80°C (with no icing)								
Ambient h range	humidity	Operating/storage: 35% to 85% (with no condensation)								
Insulation	n resistance	20 M Ω min. (at 500 VDC) between current-carrying parts and case								
Dielectric	strength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case								
Vibration	resistance	Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions								
Shock res	sistance	Destruction: 5	00m/s ² 3 times o	each in X, Y, an	d Z directions					
Degree of protectior	f n*3	IEC 60529 IP50								
Connectio	on method	Pre-wired Mod	Pre-wired Models (Standard cable length: 500 mm)							
Material		Case: Aluminu	ım alloy, Main u	nit: Aluminum, S	Shaft: SUS420J	2, Mounting Bra	acket: Galvanize	ed iron		
Weight (packed s	state)	Approx. 35 g								
Accessor	ies	Coupling, Servo Mounting Bracket (provided with the E6A2-CWZD), Hexagonal wrench, Instruction manual								

*1. An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.*2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum electrical response speed (rpm) = <u>Maximum response frequency</u> × 60 Resolution

This means that the E6A2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. *3. No protection is provided against water or oil.

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I/O Circuit Diagrams



 Output A leads B by 1/4 T±1/8 T when the shaft revolves clockwise, while A lags behind B by 1/4 T±1/8 T when the shaft revolves counterclockwise.

Safety Precautions

Refer to Warranty and Limitations of Liability.

<u> (</u>WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.

Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

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(Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder





Accessories (Order Separately) Servo Mounting Bracket Coupling

E69-C04B E69-1 Refer to Accessories for details.